

Asymptotic Analysis of Conditioned Stochastic Gradient Descent

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Joint Work with François Portier, [paper](#)

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We consider the following type of optimization problem:

$$\min_{x \in \mathbb{R}^d} \{F(x) = \mathbb{E}_{\xi}[f(x, \xi)]\}$$

∇F **hard to compute** (ERM) or **intractable** (AIS and RL)

Unbiased estimate in SGD

There is a **cheap** gradient generator $g(\cdot, \xi)$ s.t.

$$\forall x \in \mathbb{R}^d, \quad \mathbb{E}_{\xi}[g(x, \xi)] = \nabla F(x)$$

$$(SGD) \quad x_{k+1} = x_k - \alpha_{k+1} g(x_k, \xi_{k+1})$$

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- Reference book on Stochastic programming ([Shapiro et al., 2014](#))
 - Comparison with sample average approximation ([Nemirovski et al., 2009](#))

Examples

Empirical Risk Minimization (ERM). Data $z_1, \dots, z_N \in \mathcal{Z}$, loss

$\ell : \mathbb{R}^d \times \mathcal{Z} \rightarrow \mathbb{R}$, empirical risk $F(x) = N^{-1} \sum_{i=1}^N \ell(x, z_i) = \int \ell(x, z) P_N(dz)$

$$g(x, \xi) = \nabla_x \ell(x, \xi), \quad \xi \sim P_N$$

Recursive estimates (at time t , a new variable is observed $z_t \sim P$)

Adaptive importance sampling (AIS). Target function f , parametric family of samplers $\{q_x : x \in \Theta\}$, objective $F(x) = - \int \log(q_x(y)) f(y) dy$

$$g(x, \xi) = -\nabla_x \log(q_x(\xi)) \frac{f(\xi)}{q_0(\xi)}, \quad \xi \sim q_0.$$

Policy-gradient methods (RL). Algorithm REINFORCE uses a parameterized policy $\{\pi_x : x \in \Theta\}$ to optimize expected reward $F(x) = \mathbb{E}_{\xi \sim \pi_x} [\mathcal{R}(\xi)]$

$$g(x, \xi) = \mathcal{R}(\xi) \nabla_x \log \pi_x(\xi), \quad \xi \sim \pi_x.$$

Robbins and Monro (1951)

$$(SGD) \quad x_{k+1} = x_k - \alpha_{k+1}g(x_k, \xi_{k+1})$$

Stochastic approximation literature

- **Almost sure convergence:** Robbins and Siegmund (1971) and Bertsekas and Tsitsiklis (2000)
- **Rates of convergence and central limit theorem:** Sacks (1958); Kushner and Huang (1979), a law of the iterated logarithm by Pelletier (1998a)
- Two different approaches for the asymptotic normality: **diffusion-based method** (Benaïm, 1999; Pelletier, 1998b; Gadat et al., 2018); **martingale tools** (Kushner and Clark, 1978; Delyon, 1996; Hall and Heyde, 2014); **Review:** (Lai et al., 2003)

ML point of view

- Review paper: Bottou et al. (2018),
- Non asymptotic bounds (Moulines and Bach, 2011)

Conditioned-SGD (CSGD)

$$(CSGD) \quad x_{k+1} = x_k - \alpha_{k+1} C_k g(x_k, \xi_{k+1})$$

Optimal choice: $C_k \simeq \nabla^2 F(x^*)^{-1}$ (Newton's method)

Methods

- Approximation of $\nabla^2 F(x^*)^{-1}$ based on Taylor expansion (Agarwal et al., 2016).
- Ricatti's formula in *logistic regression* (Bercu et al., 2020); generalized in Boyer and Godichon-Baggioni (2020).
- **Fisher information** matrix (Amari (1998); Kakade (2002)).
- BFGS approximation in ML literature (Broyden, 1970; Fletcher, 1970; Goldfarb, 1970; Shanno, 1970; Byrd et al., 2011; Moritz et al., 2016).

Questions raised

- What condition on C_k to ensure convergence ? Asymptotic normality ?
- What conditioning matrix C_k should we choose ?
→ The optimal choice according to the asymptotic variance is the inverse of the Hessian matrix $C_k = \nabla F(x^*)^{-1}$
- Is this optimal variance achieved by a feasible algorithm ?
→ We show that the answer is positive under mild conditions on the matrix $C_k = \nabla F(x^*)^{-1}$

Some answers

- **SA literature:** Venter (1967); Fabian et al. (1973); Nevelson and Hasminskii (1976); Ruppert et al. (1985); Wei et al. (1987); Spall (2000)
- The CLT given in Pelletier (1998b) requires that $\|C_k - C^*\| \ll \|x_k - x^*\|$
- Boyer and Godichon-Baggioni (2020) works for convex functions and requires $\|C_k - C^*\| = O(n^{-s})$, $s > 0$.

$$(CSGD) \quad x_{k+1} = x_k - \alpha_{k+1} C_k g(x_k, \xi_{k+1})$$

Online and nonconvex optimization

- L -smoothness, growth conditions
- the gradient policy is allowed to change in time

A continuity result for CSGD's weak limit

- If $C_k \rightarrow C^*$ a.s., then CSGD with $C_k \simeq$ CSGD with C^*
- We give an example where efficiency is reached

Stochastic equicontinuity of the empirical process: if $(X_i)_{i \geq 1}$ is iid and $\{f_\eta\}$ with **small complexity**, then $\int (f_{\hat{\eta}_n}(x) - f_{\eta_0}(x))^2 P(dx) = o_P(1)$ implies that

$$\mathbb{G}_n \{f_{\hat{\eta}_n} - f_{\eta_0}\} = o_P(1)$$

(in words: estimating η_0 has no effect at the limit)

Mathematical Background

Goal

Find the minimizer $x^* \in \mathbb{R}^d$ of a function $F : \mathbb{R}^d \rightarrow \mathbb{R}$,

$$x^* = \arg \min_{x \in \mathbb{R}^d} F(x).$$

No convexity required on F

- F is L -smooth, coercive and the equation $\nabla F(x) = 0$ has unique solution x^* .
- $H = \nabla^2 F(x^*) \succ 0$ and $\nabla^2 F$ is continuous at x^*

Asymptotics of SGD

SGD policy (Gower et al., 2019)

$$(SGD) \quad x_{k+1} = x_k - \alpha_{k+1} g(x_k, \xi_{k+1}),$$

with $\forall x \in \mathbb{R}^d, \forall k \in \mathbb{N}$

- $\mathbb{E}[g(x, \xi_{k+1}) | \mathcal{F}_k] = \nabla F(x)$
- $\mathbb{E}[\|g(x, \xi_{k+1})\|^2 | \mathcal{F}_k] \leq 2\mathcal{L}(F(x) - F(x^*)) + \sigma^2$

Robbins-Monro condition

$$(\alpha_k)_{k \geq 1} \downarrow 0 \quad \text{s.t.} \quad \sum_{k \geq 1} \alpha_k = +\infty \quad \sum_{k \geq 1} \alpha_k^2 < +\infty$$

- In practice $\alpha_k = \alpha k^{-\beta}, \beta \in (1/2, 1]$

Theorem (Almost sure convergence)

$$x_k \rightarrow x^* \quad \text{a.s.}$$

Additional assumptions

- Liapounov condition and limiting variance Γ on the martingale increments
- $\alpha_k = \alpha k^{-\beta}$, $\beta \in (1/2, 1]$
- $(H - \kappa I) \succ 0$ with $\kappa = 1_{\{\beta=1\}} 1/2\alpha$

Theorem (Weak convergence Pelletier (1998b))

The SGD rule satisfies

$$\frac{1}{\sqrt{\alpha_k}}(x_k - x^*) \rightsquigarrow \mathcal{N}(0, \Sigma), \quad \text{as } k \rightarrow \infty$$

where Σ satisfies the following Lyapunov equation

$$(H - \kappa I)\Sigma + \Sigma(H^T - \kappa I) = \Gamma.$$

- Fastest rate for $\beta = 1$ and recover the classical $1/\sqrt{k}$ -rate.
- α large enough to ensure $H - I/(2\alpha) \succ 0$ but small enough so that $\alpha\Sigma$ small.

Variance optimality when $\beta = 1$ via Conditioning

Replace the scalar gain α by a conditioning matrix $C \in \mathbb{R}^{d \times d}$

$$x_{k+1} = x_k - \left(\frac{C}{k+1} \right) g(x_k, \xi_{k+1}).$$

with $CH - \kappa I \succ 0$.

Theorem (Deterministic Conditioning)

The sequence $(x_k)_{k \geq 0}$ (given above) satisfies

$$\sqrt{k}(x_k - x^*) \rightsquigarrow \mathcal{N}(0, \Sigma_C)$$

where Σ_C is given by the Liapounov equation

$$\left(CH - \frac{I}{2} \right) \Sigma_C + \Sigma_C \left((CH)^T - \frac{I}{2} \right) = C \Gamma C^T.$$

What conditioning matrix C should we choose ?

Optimal Variance

The choice $C^* = H^{-1}$ is optimal: $\Sigma_{C^*} \leq \Sigma_C \forall C$

- (Asymptotic efficiency) $\sqrt{k}(x_k - x^*) \rightsquigarrow \mathcal{N}(0, \Sigma_{C^*} = H^{-1}\Gamma H^{-1})$
- Averaging of standard SGD gives the same variance (Polyak and Juditsky, 1992)
- C^* is usually unknown ...

Conditioned-SGD

CSGD

$$(CSGD) \quad x_{k+1} = x_k - \alpha_{k+1} C_k g(x_k, \xi_{k+1})$$

with

$$\beta_k I_d \leq C_{k-1} \leq \gamma_k I_d$$

Extended Robbins-Monro

The sequences $(\alpha_k)_{k \geq 1}$, $(\beta_k)_{k \geq 1}$, $(\gamma_k)_{k \geq 1}$ are positive and satisfy

$$\sum_{k \geq 1} \alpha_k \beta_k = +\infty \quad \sum_{k \geq 1} (\alpha_k \gamma_k)^2 < +\infty$$

- Note that $C_k = I_d$ recovers SGD with standard Robbins-Monro.

Theorem (Almost sure convergence)

The sequence of CSGD iterates satisfies $x_k \rightarrow x^$ a.s.*

- At what speed $(x_k - x^*)$ is bounded ? Asymptotic normality ?

Mild assumption on the conditioning matrices

- $C_k \rightarrow C$ a.s.
- $(CH - \kappa I)$ positive definite with $\kappa = 1_{\{\beta=1\}}1/2\alpha$

Theorem (Weak convergence)

The sequence of CSGD satisfies

$$\frac{1}{\sqrt{\alpha_k}}(x_k - x^*) \rightsquigarrow \mathcal{N}(0, \Sigma_C), \quad \text{as } k \rightarrow \infty,$$

where Σ_C satisfies:

$$(CH - \kappa I) \Sigma_C + \Sigma_C ((CH)^T - \kappa I) = C \Gamma C^T.$$

- Continuity property (as if $C_k = C$)
- C should be close to the inverse of the Hessian $H = \nabla^2 F(x^*)$.

Sketch of the proof

In a similar spirit as in [Delyon \(1996\)](#), the proof relies on the introduction of a linear stochastic algorithm based on the approximation

$$\nabla F(x_{k-1}) \simeq H(x_{k-1} - x^*)$$

We consider the auxiliary iteration

$$\tilde{\Delta}_k = \tilde{\Delta}_{k-1} - \alpha_k K \tilde{\Delta}_{k-1} - \alpha_k C_{k-1} w_k, \quad k \geq 1$$

with $K = CH$ and $w_k = g(x_{k-1}, \xi_k) - \nabla f(x_{k-1})$. Then we show that

$$(x_k - x^*) - \tilde{\Delta}_k = o_{\mathbb{P}}(\sqrt{\alpha_k})$$

The analysis of $\tilde{\Delta}_k / \sqrt{\alpha_k}$ is carried out with martingale tools.

An effective algorithm

Hessian generator

There exists Hessian generator $H(\cdot, \xi'_{k+1})$ such that

$$\forall k \geq 1, \forall x \quad \mathbb{E} [H(x, \xi'_{k+1}) | \mathcal{F}_k] = \nabla^2 F(x).$$

Average past estimates with some weights

$$\Phi_k = \sum_{j=0}^k \nu_{j,k} H(x_j, \xi'_{j+1}),$$

where $\nu_{j,k} \propto \exp(-\eta \|x_j - x_k\|_1)$ is such that $\sum_{j=0}^k \nu_{j,k} = 1$.

Regularization

$$\forall k \in \mathbb{N}, \quad C_k = (\Phi_k + \gamma_{k+1}^{-1} I_d)^{-1}$$

Asymptotic Efficiency of CSGD

Proposition

If $H(x, \xi)$ bounded and $\gamma_k \rightarrow \infty$ then $C_k \rightarrow H^{-1}$ a.s
(proof: Freedman's inequality and the Cesaro Lemma)

Corollary (Asymptotic optimality)

Let $(x_k)_{k \geq 0}$ be the CSGD iterates with $\alpha_k = 1/k$ and C_k given before. If $\sum_{k \geq 1} (\gamma_k/k)^2 < \infty$, we have

$$\sqrt{k}(x_k - x^*) \rightsquigarrow \mathcal{N}(0, H^{-1}\Gamma H^{-1}), \quad \text{as } k \rightarrow \infty$$

- Asymptotic optimality is reached !
- Practical choice $\alpha_k = 1/k$: removes the assumption $2\alpha H \succ I$

Corollary (Asymptotic of excess risk)

$$k(F(x_k) - F(x^*)) \rightsquigarrow \sum_{k=1}^d \lambda_k Z_k^2,$$

$(Z_1, \dots, Z_d) \sim \mathcal{N}(0, I_d)$ and $(\lambda_k)_{k=1}^d$ are eigenvalues of $H^{-1/2}\Gamma H^{-1/2}$

Numerical Experiments: ERM

- We apply ERM to regularized **regression** and **classification** problems.

Ridge regression

Given a data matrix $X = (x_{i,j}) \in \mathbb{R}^{n \times p}$ with labels $y \in \mathbb{R}^n$ and a regularization parameter $\mu > 0$. Consider

$$\min_{\theta \in \mathbb{R}^d} F(\theta) = \frac{1}{2n} \sum_{i=1}^n (y_i - \sum_{j=1}^d x_{i,j} \theta_j)^2 + \frac{\mu}{2} \|\theta\|_2^2$$

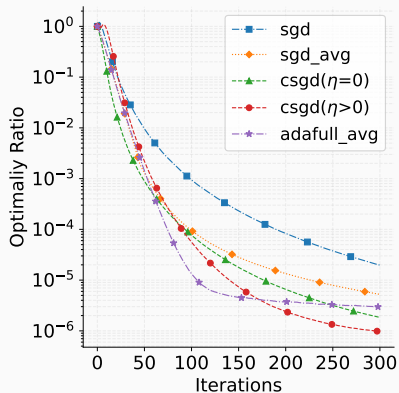
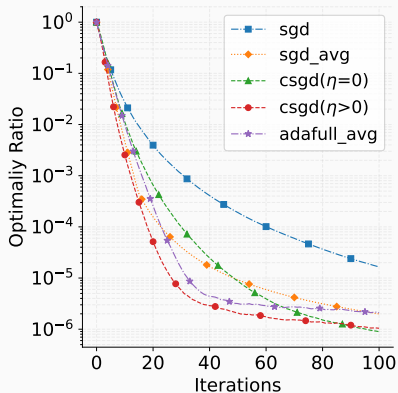
logistic regression

Given a data matrix $X = (x_{i,j}) \in \mathbb{R}^{n \times p}$ with labels $y \in \mathbb{R}^n$ and a regularization parameter $\mu > 0$. Consider

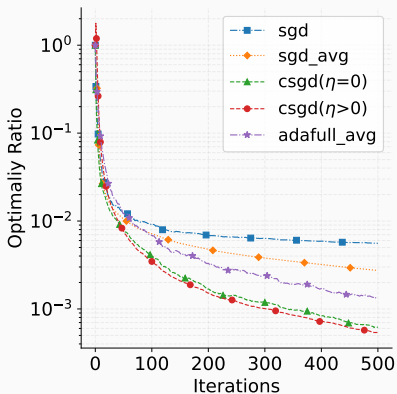
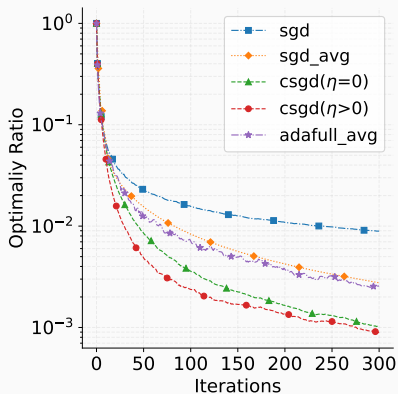
$$\min_{\theta \in \mathbb{R}^d} F(\theta) = \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-y_i \sum_{j=1}^d x_{i,j} \theta_j)) + \mu \|\theta\|_2^2$$

- Setting $n = 10,000$, $d \in \{20, 100\}$, $\mu = 1/n$.

Numerical Experiments: synthetic $d = 20$ and $d = 100$



Numerical Experiments: Boston and Diabetes datasets



Conclusion

Contributions

- Almost sure convergence of CSGD in a **non convex setting**
- Asymptotic normality: **Equi-continuity property** when $C_k \rightarrow C$
- Definition of an algorithm that achieves **efficiency**

Applications

- When the Hessian is known exactly without noise
- Dynamical update of Hessian estimates (BFGS)
- Particular choice of diagonal conditioning matrix with weights: perform coordinate sampling, see our [paper](#) at *Journal of Machine Learning Research, 2022*

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